

# ROBOTIQ SCREWDRIVING *SOLUTION*

Elevate your workforce

- Consistent screwdriving around the clock.
- 5-min production changeovers.
- Complete solution designed for flexible automation of your screwdriving tasks.



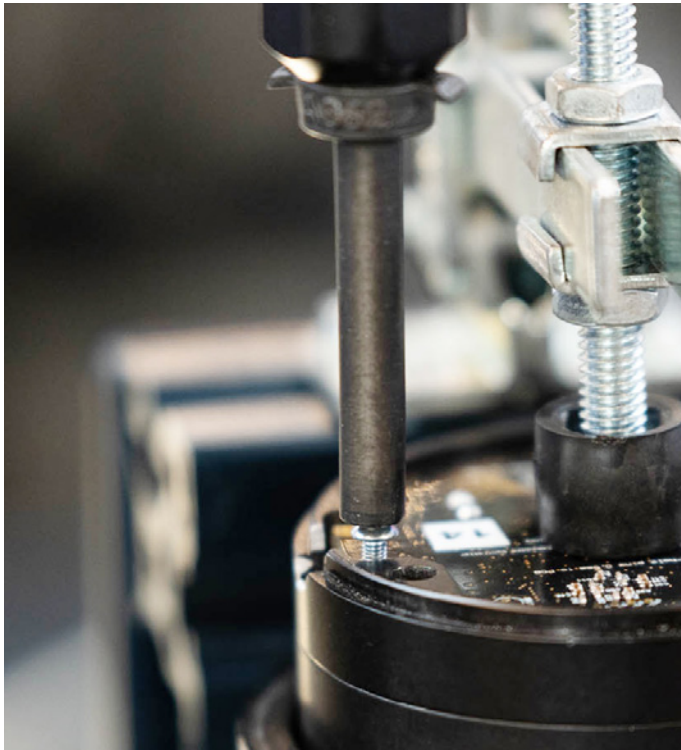
## **Fewer injuries and a happier workforce**

When you automate a screwdriving task, you keep employees from harm and can redirect them to value-added tasks. Elevate your workforce with a simple and easy-to-use automation solution.

# START PRODUCTION FASTER

# CONSISTENT SCREWDRIVING AROUND THE CLOCK

- Free workers for higher-value tasks
- Reduce repetitive strain injuries
- Improve product quality
- Solve labor shortages



## A single fastening solution to handle production changeovers **in small-screw assembly**

Deploy and master your robotic screwdriving application by adding Robotiq Screwdriving Solution to a UR cobot. So intuitive, no robotics experience is required.

Get a simple, cost-effective automation solution, and say hello to consistent screwdriving around the clock.



## Designed for **flexible automation**

- Automate easily, without massive investment
- Intuitive to deploy and duplicate
- 5-min production changeovers

# PROGRAM YOUR APPLICATION IN 2 EASY STEPS

## 1

### PICK SCREW COMMAND

Command

Graphics

Variables

#### Pick Screw

Select the digital inputs of the Screw Feeder.

Feeder status  ●

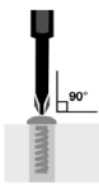
Screw ready  ●

☒ Retry on failure

Slightly insert the screwdriving bit in the screw drive and tap on Set pick position.

The approach position is preset with a 10 mm offset.

Tap the Test button to cycle through the Pick Screw program.



## 2

### DRIVE SCREW COMMAND

Command

Graphics

Variables

#### Drive Screw

Stop condition   Nm

Tool speed  RPM

Force applied on screw  N

☒ Advanced settings:

Angle before ramp down  deg

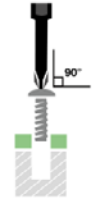
☐ Left-Hand Threads

Error Conditions

☐ Retry on failure

☐ Distance tolerance ( $\pm$ )  mm

☒ Timeout  s



**Control the screwdriver** directly from the UR Toolbar to use, test or set it.

**Seamlessly integrate** the force sensing, vacuum, cobot, screwdriver, and screw feeder.

**Automatically apply error-proofing functions** to improve productivity and quality.

## SCREWDRIVER

No external controller

Compact and lightweight

Robust vacuum system transports screws of any material

Off-the-shelf compliant vacuum sleeves accommodate your part tolerances

3.5-inch bits and vacuum sleeves for hard-to-reach locations



## SCREW FEEDER

No additional parts needed to adapt to various screw sizes

300-cc screw chamber volume

Dual sensor indicates **screw ready** and **screw cleared from workspace**

Mounting bracket included

Robust industrial exterior finish



Intuitive adjustment with real-time confirmation

## SPECIFICATIONS

Screwdriver SD-100	Min	Typical	Max
Torque range	1 Nm 9 in-lbs	-	4 Nm 35 in-lbs
Torque accuracy	-	±10% <sup>1</sup>	-
Screw diameter	M2.5 #3	-	M5 <sup>2</sup> #10
Speed	1 RPM	-	500 RPM
Air consumption	-	80 L/min	-
Weight	1.5 kg 3.3 lb		
Dimensions	280 mm x 152 mm x 57 mm 11 x 6 x 2 1/4 in.		
Warranty	2M cycles under normal operation		
ESD-safe	Yes		

1. Value at initial factory calibration. Accuracy typically increases when calibrated in operating conditions, depending on joint materials.  
 2. Over M4 or #8, validate your use case with our team of coaches.

Screw Feeder SF-300	Min	Max
Screw diameter	M2.5 #3	M5 <sup>1</sup> #10
Screw length	6 mm <sup>2</sup> 1/4 in	25 mm 1 in
Screw head height	-	10 mm 3/8 in
Typical feed rate	-	3 s per screw
Screw chamber volume	300 cc	
Dimensions (W x D x H)	157 mm x 286 mm x 171 mm 6.18 x 11.25 x 6.73 in.	
Power supply	120/220V AC to 24V DC	
Weight	5.2 kg 11.4 lb	
Warranty	2M cycles under normal operation	
ESD-safe	Yes	

1. Over M4 or #8, validate your use case with our team of coaches.  
 2. For socket head screws, the minimum screw length is 10 mm, but ±4 mm may be possible.

## OVERVIEW

Feature	What is it?	Advantage
<b>Error-proofing</b>	<p>Pre-programmed error-detection and recovery functions:</p> <ul style="list-style-type: none"> <li>• Screw presence detection.</li> <li>• Torque and screw position control.</li> <li>• OK/Not OK confirmation.</li> </ul>	<ul style="list-style-type: none"> <li>• Ensures correct torque is applied.</li> <li>• Eliminates risk in the process.</li> <li>• Prevents fastening failures.</li> <li>• Saves programming time.</li> </ul>
<b>Vacuum transportation system</b>	<p>Integrated vacuum system that allows for reliable screw transport while ensuring maximal slender reach.</p>	<ul style="list-style-type: none"> <li>• Allows the robot to validate screw presence at all times.</li> <li>• Allows the system to transport screws of any material.</li> <li>• Requires no customization.</li> <li>• Enables maximal reach into tight spaces.</li> </ul>
<b>One-SKU solution</b>	<p>With one SKU, you get the screwdriver, screw feeder, screwdriver bits and vacuum sleeves, screwdriving URCap, and the latest force-sensing technology.</p>	<ul style="list-style-type: none"> <li>• Simplified ordering.</li> <li>• Simplified tracking.</li> <li>• Simplified management of spare parts.</li> <li>• No need to purchase additional parts.</li> </ul>
<b>Dual sensors in screw feeder</b>	<p>Dual sensor indicates both screw ready and screw cleared from workspace.</p>	<ul style="list-style-type: none"> <li>• Prevent pick command from activating if a screw is not ready.</li> <li>• Avoid collisions.</li> <li>• Coordinate robot and screw feeder movements.</li> </ul>
<b>Automated communication between every component</b>	<p>Getting separate components (screw feeder, screwdriver, robot, and more) to communicate has never been easier.</p>	<ul style="list-style-type: none"> <li>• Simple programming to help you master your processes.</li> <li>• Decrease deployment time.</li> </ul>
<b>Designed to reach tight spaces</b>	<p>We've designed a compact and lightweight screwdriver with flexible vacuum sleeves for optimum screwdriving.</p>	<ul style="list-style-type: none"> <li>• Allows screwdriving in chamber holes.</li> <li>• Allows screwdriving in tight spaces.</li> </ul>
<b>Open program tree</b>	<p>Robotiq Screwdriving URCap integrates the force sensing and force control functions to automatically program a pick and a screw, but the program tree is open for you to develop any advanced programming sequence.</p>	<ul style="list-style-type: none"> <li>• Adapt the solution to fit your unique application.</li> </ul>



# SERVICES

At Robotiq, we strive to free more human hands from repetitive tasks. To do so, we offer tools and services to empower you to deploy your project on your own and master your processes.

Our team of coaches: Benoît, David, Marc-Antoine and Paul



## SCREWDRIVING PROOF OF CONCEPT

Our team of coaches is here to help you prove that our solution can work for your application, as well as avoid technical issues and simplify your introduction to the robot world.

### Examples services:

- Demonstrate application fit
- Validate cycle time
- Demonstrate repeatability

## REMOTE AND ONSITE TRAINING FOR ROBOTIQ SCREWDRIVING SOLUTION

Our training aims to fast-track your introduction to the ever-growing collaborative robot industry.

- Intro to cobots
- Solution installation
- Solution operation
- Troubleshooting and maintenance
- Calibration
- Force Copilot for Assembly

START  
PRODUCTION  
FASTER

## WHAT'S NEXT?

Get access to the  
Screwdriving Solution eLearning module at  
[elearning.robotiq.com](https://elearning.robotiq.com)

For further information  
[robotiq.com/support](https://robotiq.com/support)  
[iss@robotiq.com](mailto:iss@robotiq.com)  
1-888-Robotiq



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